Contact your local distributor at

www.onrobot.com







About OnRobot

OnRobot is a global company headquartered in Odense, the capital of the robotic cluster in Denmark. Our products are sold through a network of dedicated distributors.

sales@onrobot.com www.onrobot.com



OnRobot A/S Teglvaerksvej 47H 5220 Odense SØ Denmark +45 53 53 57 37

One Stop Shop for End-of-Arm Tooling

OnRobot provides all types of gripping and sensing solutions for industrial automation



We deliver savings, You increase your profit

OnRobot provides state of the art gripping and sensing technologies for companies interested in industrial automation. You can find all types of sensing systems for collaborative applications like assembly, surface finishing, pick and place, machine tending or testing.

It has never been easier to deploy your intelligent robot. With deployment time reduced by 30%, OnRobot products are the easy choice in short lead time projects and environments where robots are often re-deployed.

OnRobot develops gripping and sensing systems that not only operate efficiently. By using the true Plug&Produce OnRobot solutions, you get the ultimate installation and programming convenience and re-deployment has never been faster.

Gripping and sensing systems designed for the ultimate installation and programming convenience





POLYSKIN TACTILE GRIPPER Cost-effective material handling with built-in force control

- Individually actuated fingers
- Force or position controlled gripping
- ⊙ 0-70 mm stroke
- Sump detection
- Thermal sensor

OnRobot tactile grippers provide accurate positionorientation and force data for all of your automation needs. It has the ability to assess grip quality and prevent dropping items in a cost effective way.

APPLICATIONS







Pick & Place



TECHNICAL DETAILS

SPECIFICATION OR FEATURE	VALUE / COMMENTS	
GRIPPER		
Total stroke	0-70mm	
Grip force range	10-400 N (total for both fingers)	
Maximum Payload	10 kg, but also depends on coefficient of friction	
Holds part on power loss?	Yes	
SENSORS		
Sensitivity	0.3 N	
Thermal Sensing	-20 to 125 ℃	

Compatible with Universal Robots, Kawasaki



GECKO GRIPPER

Attach like a gecko and automate more

The nature inspired OnRobot gecko technology makes it possible to attach and lift any kind of flat and smooth surfaces. Fast and easy gripping technology for pick & place applications.

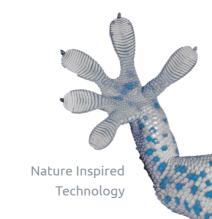
APPLICATIONS



Packaging & Palletizing



Pick & Place



arobot

GECKO GRIPPER

TECHNICAL DETAILS

MAXIMUM PAYLOAD IN KG	POLISHED STEEL / ACRYLIC/ GLASS/ SHEET METAL
Food grade environment	4.1 / 4.1 / 3.3 / 3.1
Other environments - with Cleaning System	1.6 / 1.6 / 1.3 / 1.3
SPECIFICATION OR FEATURE	VALUE / COMMENTS
GRIPPER	
Holds part on power loss?	Yes
Proximity sensor range	0-260mm
PAD	
Change-out interval	100,000 cycles



RG2 AND RG6 GRIPPERS

Plug&Produce grippers

for higher ROI

- Adjustable gripper mounting

- Oppth compensation
- Customizable fingertips
- Oual gripper

RG2/RG6 collaborative grippers are true Plug & Produce solutions. The fast installation and simple programming reduce your deployment time by 30%.



APPLICATIONS





Machine Tending



Packaging & Palletizing



Assembly



Pick & Place

TECHNICAL DETAILS

PARAMETER	RG2	RG6
Payload	2 kg	6 kg
Gripping Force (1N resolution)	3-40N	25–120N
Total Stroke (1mm resolution)	110mm	160mm
Stroke Time (0-110/40-20)	950ms/200ms	950ms/200ms
Product Weight	650g	1000g
Feedback	Force (3-40N) and	Force (25-120N) and
	width (0-110mm) detection	width (0-160mm) detection

Compatible with Universal Robots, Kawasaki

Compatible with **Universal Robots**



RG2-FT GRIPPER

See and touch objects with intelligent gripping

- Detects workpiece using proximity sensor
- Detects risk of slipping before it happens

- Force/Torque sensor for enabling precise machine tending, assembly jobs and collaborative operations

You can automate high precision assembly tasks with OnRobot RG2-FT. The in-built 6 axis F/T sensors at the fingertips provide extremely accurate gripping for better production quality

APPLICATIONS



Assembly



Pick & Place



Machine Tending



HEX-E, HEX-H F/T SENSOR

Automation made simple

by a sense of touch

OPTOFORCE TECHNOLOGY

- Functions like center pointing, insertion, hand guiding or path recording

The pre-programmed OnRobot force sensing applications and the intuitive user interface ensure a quicker integration and easier operation with the sense of touch.

APPLICATIONS



Assembly



Surface Finishing: Deburring, Grinding, Polishing



Quality Testing & Inspection

TECHNICAL DETAILS

GENERAL PROPERTIES	MINIMUM	TY	PICAL	MAXIMUM
Total stroke	0 mm		-	100 mm
Finger position resolution		0.	1 mm	
Gripping force (adjustable)				40 N
Gripping speed	55 mm/s	110	mm/s	184 mm/s
FORCE SENSOR	Fxy	Fz	Тху	Tz
Nominal capacity (N.C)	20 N	20 N	0.8 Nm	0.5 Nm
Noise free resolution	0,0098 N	0,039 N	0.008 Nm	0.005 Nm
PROXIMITY SENSOR	MINIMUM	TY	TYPICAL	
Sensing range	0 mm		-	
Resolution	3 mm	1	1 mm 0	

TECHNICAL DETAILS

PARAMETER	HEX-E - HIGH PRECISION	HEX-H - LOW DEFORMATION
Size	Ø70x37.5 mm	Ø70x37.5 mm
Rated Fx, y, z (all directions)	200 N	200 N
Rated Torque	Tz: 6,5 Nm Txy: 10 Nm	Tz: 13 Nm Txy: 20 Nm
Resolution (Noisefree)	Fxy: 0,2 N Fz: 0,8 N	Fxy: 0,5 N Fz: 1 N
Rated Deformation	Fxy: ±1,7 mm Fz: ±0,3 mm	Fxy: ±0,6 mm Fz: ±0,25 mm